

STELLARATOR OPTIMIZATION WITH JULIA, PART 2

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GOAL: A NEW TOOLCHAIN FOR STELLARATOR OPTIMIZATION

- Written primarily in the Julia language
 - ▶ Utilize the flexibility of Julia and the Julia package ecosystem while leveraging the native performance of Julia
- Flexible and modular: adding/subtracting physics components should not break the implementation
 - ▶ Add different equilibrium solvers, GPU vs. CPU physics targets...
- Physics targets should be easily accessible as standalone functions from the Julia REPL to perform detailed analysis on a faster timescale
 - ▶ *Interact* with the data, rather than compile & run

STELLARATOR OPTIMIZATION COMPONENTS

- Stellarator optimization requires the following components:
 - ▶ Resource manager (MPI processors, distributed processors, threads...)
 - ▶ Equilibrium solvers (VMEC, SPEC...)
 - ▶ Optimization infrastructure/context (MANGO, Optim.jl...)
 - ▶ Geometry functions (Coordinate vectors, ∇B , metric components,...)

<https://gitlab.com/wistell>

- PlasmEquilibriumToolkit.jl (PET.jl)
- VMEC.jl
- lasso.jl

- Package for defining, manipulating geometric quantities from 3D magnetic equilibria
- Currently provides the following utilities
 - ▶ Abstract types for magnetic equilibria and coordinates:
`MagneticEquilibrium`, `MagneticCoordinates`
 - ▶ Coordinate systems:
`{PestCoordinates, BoozerCoordinates, ...}` `<: MagneticCoordinates`
 - ▶ Interfaces with `CoordinateTransformations.jl`:
`{CylindricalFromPest, PestFromFlux, ...}` `<: Transformation`
 - ▶ Basis Vectors:
 - Contravariant: $\nabla\psi, \nabla\alpha, \nabla\theta, \dots$
 - Covariant: $\mathbf{e}_\psi, \mathbf{e}_\alpha, \dots$
 - ▶ Vector Field Transformations:
`{ContravariantFromCovariant, ...}` `<: Transformation`
 - ▶ Abstractions for computing field quantities like $\nabla B, \kappa_n, \kappa_g$

- Abstract types provide a convenient way to extend methods to different equilibrium types:

```
function covariant_basis(t::Transformation,x::AbstractArray{T},eq::MagneticEquilibrium)
  where T <: MagneticCoordinates
    res = Array{BasisVectors{typeof(getfield(first(x),1))},ndims(x)}(undef,size(x))
    map!(i->covariant_basis(t,i,eq),res,x)
    return res
end
```

- Immediately implemented by new equilibrium solver (e.g. SPEC) and/or new magnetic coordinates (e.g. Hamada)

- Package for interfacing with VMEC equilibria
- Provides different data structures for VMEC data
 - `{VmecData, Vmec, VmecSurface} <: MagneticEquilibrium`
 - Uses cubic spline interpolation to compute surface dependence
- Defines VMEC-specific coordinates and coordinate transformations
 - `VmecCoordinates <: MagneticCoordinates`
 - `PestFromVmec, BoozerFromVmec, ... <: Transformation`
- Read NetCDF files, write HDF5 files
- Fortran interface implemented to run PARVMEC from Julia, retrieve results
emphin memory

EXAMPLE: COORDINATE TRANSFORMATION

- Compute the VMEC coordinates for a field line at $s = 0.5$

```
julia> wout = NetCDF.open("wout_aten.nc"); vmec, vmec_data = readVmecWout(wout);
julia> s = 0.5; psi = s*vmec.phi(1.0)/(2*pi);
julia> alpha = 0.0; zeta = -pi:pi/2:pi; #Define PEST coordinates
julia> vmec_surface = VmecSurface(s,vmec); #Extract the VMEC data at s = 0.5
julia> pc = PestCoordinates(psi,alpha,zeta); # Generates a vector of PEST Coordinates
julia> vc = VmecFromPest()(pc,vmec_surface) # Generates the VMEC coordinates
5-element Array{VmecCoordinates{Float64,Float64},1}:
VmecCoordinates(s=0.5, theta=-3.485668445213474, zeta=-3.141592653589793)
VmecCoordinates(s=0.5, theta=-1.6411857501972285, zeta=-1.5707963267948966)
VmecCoordinates(s=0.5, theta=0.0, zeta=0.0)
VmecCoordinates(s=0.5, theta=1.6411857501972282, zeta=1.5707963267948966)
VmecCoordinates(s=0.5, theta=3.485668445213474, zeta=3.141592653589793)
```

EXAMPLE: QUASISYMMETRY

- From ATEN equilibrium, compute quasisymmetry deviation on each surface
 - ▶ Specify $m_{QS} = 1$, $n_{QS} = 4$ with $m_{Boozer} = n_{Boozer} = 8$
 - ▶ Use 32 hardware threads

```
julia> wout = NetCDF.open("wout_aten.nc"); vmec, vmec_data = readVmecWout(wout);
julia> vmec_surfaces = map(s->VmecSurface(s,vmec),0.02:0.02:0.98); # Selects the surfaces
julia> @btime quasisymmetry(1,4,8,8,vmec_surfaces)
779.157 ms (28077361 allocations: 1.80 GiB)
49-element Array{Float64,1}:
0.00847798155710977
0.008143611712198736
0.007862450747713788
...
```

- Fast, but memory intensive calculation due to the Boozer transformation

Lightweight Architecture for Scalable Stellarator Optimization (lasso)

- Glue layer for stellarator optimization specific problems
 - ▶ Expose different optimization libraries and methods (MANGO, Optim.jl,...)
 - ▶ Provide standardized interface for computing physics targets, defining optimization variables
 - ▶ Define submodules for specific implementations, currently:
 - VmecOpt: functions for translating VMEC quantities
 - Mango: interface functions for Mango
 - ▶ Records optimization variables and targets in top-level dictionaries:
 - `lassoOptVariables`, `lassoOptTargets`

SPECIFYING TARGETS

- Two different types of physics target, subtypes of AbstractOptTarget:

```
struct Target{TargetType,WeightType} <: AbstractOptTarget
  target::TargetType # The target value
  weight::WeightType # The target weight
  inputArgs::Dict{Symbol,Any} # Inputs for target calculation
  mod::Module # Module containing target code
end
```

```
struct LeastSquaresTarget{TargetType,SigmaType,WeightType} <: AbstractOptTarget
  target::TargetType # The target value
  sigma::SigmaType # The target sigma in a LSQ formulation
  weight::WeightType # The target weight
  inputArgs::Dict{Symbol,Any} # Inputs for target calculation
  mod::Module # Module containing target code
end
```

SPECIFYING TARGETS

- Macros implemented to define optimization targets
- Arguments for the target can be passed as Julia Expressions; the last expression is always the target Module

```
@target(value,weight,exprs...)
```

```
@leastsquarestarget(value,sigma,weight,exprs...)
```

- ▶ Invocation adds an entry to `lassoOptTargets`

- General routine for objective function:

```
function objective(args...)
```

```
    objFun = 0.0
```

```
    for (index,target) in lassoOptTargets
```

```
        objFun += target.weight*(target.mod.computeTarget(target.inputArgs,args...)
                                - target.target)
```

```
    end
```

```
    return objFun
```

```
end
```

- `args...` are implementation-specific arguments (e.g. VMEC/SPEC equilibrium, MPI communicator, threads, etc.)

SPECIFYING VARIABLES

- Macros implemented to define optimization variables

- ▶ Invocation adds an entry to `lassoOptVariables`

- Example - `VmecOpt` input:

- ▶ Specify *any* VMEC input variable

- `@VmecVariable(name[,value,weight=1.0,recompute=true])`

- ▶ Default value taken from input file

```
&VmecOpt
inputFile = /home/bfaber/projects/julia/VMEC.jl/input.aten
vmecLib = /home/bfaber/projects/VMEC2000/lib/libvmec.so
@VmecVariable(rbc(0,0))
@VmecVariable(zbs(0,3))
@VmecVariable(zbs(-3,1))
@VmecVariable(rbc(-2,1))
...
```

FLEXIBILITY AT RUNTIME

- lasso links to geometry, target modules at dynamically
- Parses input file, records Module information as a Dict
- ‘&Module’ similar to Fortran namelist
- Example:

```
&VMEC.QuasiSymmetry
mQS = 1
nQS = 4
mBoozer = 16
nBoozer = 16
@leastsquarestarget(0.0,1.0,1.0,surfaceLabel=0.3)
@leastsquarestarget(0.0,1.0,1.0,surfaceLabel=0.4)
```

```
julia> lassoOptTargets
Dict{Int64,AbstractOptTarget} with 2 entries:
 1 => LeastSquaresTarget(0.0,1.0,1.0,Dict{Symbol,Any}(:mQS=>1,:nQS=>4,:mBoozer=>16,
               :nBoozer=>16,:surfaceLabel=>0.3),VMEC.QuasiSymmetry)
...
```

OPTIMIZATION WITH MPI AND MANGO

- Multiple routes for parallelism: fine-grained threads, independent distributed processes, MPI
 - ▶ VMEC currently paralleized via MPI, natural to use MPI-based optimization
- Wrap MANGO as a callable library using CxxWrap.jl $\Rightarrow$ MANGO optimization objects can be managed from Julia
 - ▶ Immediately exposes number of MPI-based optimization algorithms
- Idea: MANGO controls the optimization context, but compute the residual function in *Julia*
 - ▶ Writing target functions in Julia allows us to leverage packages from the Julia ecosystem, for example:
 - Spline libraries, root finding algorithms, adaptive integration (Gauss-Konrad, Double Exponential...)
 - ▶ Leverage advanced features like automatic differentiation, GPU interfaces in future applications

OPTIMIZATION WITH MPI AND MANGO

```
function Mango.optimize()  
    ...  
    #Setup optimization problem  
    ...  
    prob = MangoWrapper.Least_squares_problem(nPar,stateVec,nTerms,targetes,sigmas,best_func)  
    residualFunction_cxx = @safe_cfunction(residualFunction,Cvoid,  
        (CxxPtr{Cint},ConstCxxPtr{Cdouble},CxxPtr{Cint},  
         CxxPtr{Cdouble},CxxPtr{Cint},  
         CxxPtr{MangoWrapper.Problem},Ptr{Cvoid}))  
    MangoWrapper.set_residual_function(prob,residualFunction_cxx)  
    if head  
        best_residual = MangoWrapper.optimize(prob)  
        MangoWrapper.stop_workers(prob)  
    else  
        worker(prob)  
        best_residual = nothing  
    end  
    best_residual = MPI.bcast(best_residual,0,comm)  
    return best_residual  
end
```

OPTIMIZATION WITH MPI AND MANGO: COMPUTING RESIDUAL

■ Group leader:

```
function residualFunction(nPar, stateVecPtr, nTerms, resPtr, failed, probPtr, userData)
    comm = MangoWrapper.get_comm_worker_groups(probPtr) # Get the MPI group comm
    stateVec = unsafe_load(stateVecPtr) # Get state vector from mango
    MPI.Bcast!(stateVec, 0, comm) # Broadcast the state vector to worker group
    translate!(stateVec) # Translates between state vector entries and VMEC inputs
    vmec = VMEC.run_vmec(comm, VmecOpt.vmecInput, VmecOpt.vmecLib) # Run VMEC
    residual = compute_residual(vmec, comm) # Compute residual using Julia functions
    unsafe_store!(residualPtr, residual) # Pass residual to mango
end
```

■ Group worker:

```
function worker(prob::MangoWrapper.Problem)
    comm = MangoWrapper.get_comm_worker_groups(prob)
    stateVector = Vector{Float64}(undef, nParameters)
    while MangoWrapper.continue_worker_loop(prob)
        MPI.Bcast!(stateVector, 0, comm) # Wait for the next state vector
        translate!(stateVector)
        vmec = VMEC.runVmec(comm, vmecInput, vmecLib) # Run VMEC on group comm
        compute_residual(vmec, comm) # Compute residual using Julia functions
    end
end
```

OPTIMIZATION WITH MPI AND MANGO: COMPUTING RESIDUAL

- Computing residual function particularly simple. In Mango:

```
function compute_residual(vmec::Vmec)
    residual = Vector{Float64}(undef,length(lassoOptTargets))
    if !isnan(vmec.iota(0.99)) && !isapprox(vmec.iota(0.99),0.0) && !isinf(vmec.iota(0.99))
        residual = lasso.computeTarget(vmec)
    else
        residual = fill(1e10,length(lassoOptTargets))
    end
end
```

- In lasso:

```
function computeTarget(vmec)
    targetValues = Vector{Float64}(undef,length(lassoOptTargets))
    for (key, target) in lassoOptTargets
        # Use the computeTarget function defined in each target module
        targetValues[key] = target.mod.computeTarget(target.inputArgs,vmec)
    end
    return targetValues
end
```

WRITING PHYSICS TARGETS

■ Physics targets are wrapped in a Module

- ▶ Module must provide the computeTarget function:

```
function computeTarget(inputArgs::Dict{Symbol,Any},args...)
```

- ▶ The first argument is always a dictionary with the necessary input parameters
- ▶ Optionally provide parseInputLines function to read from input file

```
module VMEC.QuasiSymmetry
```

```
using VMEC
```

```
#Specialized function for computing QS on a VmecSurface
```

```
function computeTarget(args::Dict{Symbol,Any},vmecSurface::VmecSurface{N,T}) where {N,T}
```

```
    if args[:surfaceLabel] != vmecSurface.s
```

```
        throw(error("Input surface label and VmecSurface label do not match!"))
```

```
    end
```

```
    return quasisymmetry(args[:mQS],args[:nQS],args[:mBoozer],args[:nBoozer],vmecSurface)
```

```
end
```

```
# More complicated function for computing quasisymmetry target
```

```
function quasisymmetry(m,n,mBoozer,nBoozer,vmecSurface)
```

```
    ...
```

```
end
```

```
end
```

WRITING PHYSICS TARGETS

- Simple targets, like $\iota(s)$, need to also be wrapped:

```
module VMEC.RotationalTransform
using VMEC
function computeTarget(args::Dict{Symbol,Any},vmec::Vmec)
    return vmec.iota(args[:surfaceLabel])
end
end
```

- Slightly more overhead needed for simple targets, but provides a common way of computing physics targets regardless of form (simple VMEC quantity vs. complex functional dependence)

CURRENT STATUS + FUTURE DIRECTIONS

- VMEC-based optimization calculations can now be performed with Julia-defined physics targets
 - ▶ Tested with quasisymmetry, rotational transform, Γ_c targets
 - ▶ More extensive testing needed: parallelized target evaluation, running on a cluster...
- Next steps:
 - ▶ Adding MPI-based turbulence saturation metric
 - ▶ Writing *a lot* of documentation and examples
 - ▶ Implementing unit tests and code coverage metrics
 - ▶ Getting feedback from **you**