

Fast modelling of energetic ion neoclassical losses in stellarators

José Luis Velasco¹,
I. Calvo¹, S. Mulas¹, E. Sánchez¹, F.I. Parra², A. Cappa¹

¹Laboratorio Nacional de Fusión, CIEMAT

²Rudolf Peierls Centre for Theoretical Physics, University of Oxford



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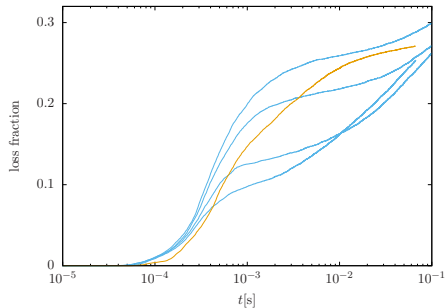
Goal

Energetic ions are lost via neoclassical mechanisms in stellarators. Two basic time scales:

- Prompt losses.
- Stochastic losses.

Prompt losses correspond to energetic ions of higher kinetic energy:

- Deleterious effect.
- Modelling can be collisionless, limited to trapped ions and without E_r .



(In all this work: collisionless simulations with ASCOT, 50 keV ions mimicking α distribution).

Goal of this work: develop a **fast model for the evaluation of prompt losses of energetic ions in stellarators** (paper to be submitted).

- Useful for optimization and characterization of parameter space, but also for understanding key features.

Long term goal: **fast and accurate simulations of energetic ions** (in preparation, final slides).

Notation

- Spatial coordinates: normalized toroidal flux ($s = \Psi_t / \Psi_{LCMS}$), field label ($\alpha = \theta - \iota \zeta$) and arc length (l).
- Velocity coordinates: velocity (v) and pitch angle ($\lambda = 2\mu/v^2$). Constants of motion.

For trapped particles:

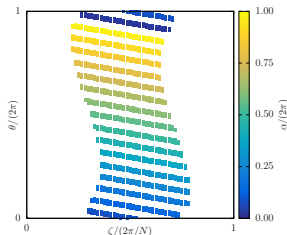
$$\overline{\mathbf{v}_M \cdot \nabla s} = \frac{m}{Ze\Psi_t\tau_b} \partial_\alpha J, \quad \overline{\mathbf{v}_M \cdot \nabla \alpha} = -\frac{m}{Ze\Psi_t\tau_b} \partial_s J$$

$$J(s, \alpha, v, \lambda) = 2v \int_{l_{b1}}^{l_{b2}} dl \sqrt{1 - \lambda B}, \quad \bar{f} = \frac{2}{v\tau_b} \int_{l_{b1}}^{l_{b2}} dl \frac{f}{\sqrt{1 - \lambda B}}, \quad \tau_b = \frac{2}{v} \int_{l_{b1}}^{l_{b2}} \frac{dl}{\sqrt{1 - \lambda B}}$$

($f(s, \alpha, l, \lambda, v)$ is an arbitrary function).

- $|\partial_\alpha J / \partial_s J|$ small: poloidal precession on the flux-surface.
- $|\partial_\alpha J / \partial_s J|$ large: large radial excursions, **superbanana orbits**.

Energetic ions move in (s, α) space at constant J .

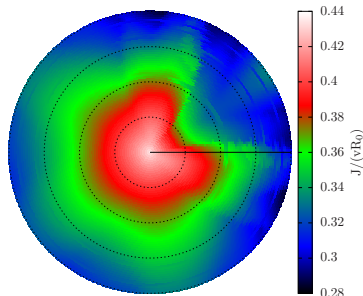
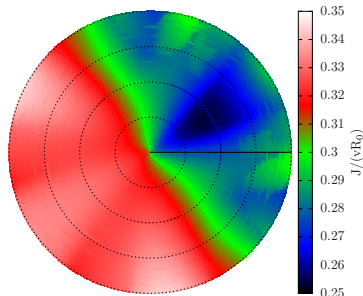


Energetic ion confinement and contours of J

$\beta = 1\%$

$(\lambda = 0.41/T)$

$\beta = 4\%$



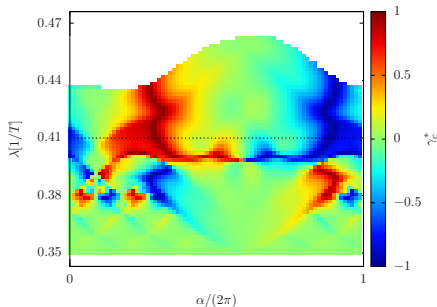
- For W7-X (KJM configuration), when β increases, J -contours tend to be aligned to s -contours and J tends to be monotonically decreasing with s : maximum- J property [Helander, PoP (2013)].
- Configurations satisfying exactly the maximum- J condition have no superbananas, because $\partial_s J$ does not vanish.

Radially local description of J -maps: why?

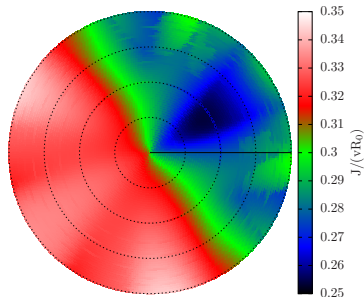
- Radially global description requires a radially global code:
 - ▶ Does not exist, except for guiding-center MC codes (but see final slides!).
 - ▶ Additional radial variable $\Rightarrow$ higher computing cost.
- Stellarator optimization tends to use radially local approach:
 - ▶ Targets, proxies... evaluated at discrete flux-surfaces.
 - ▶ Theory predicts that perfect optimization (w.r.t some criteria) cannot be achieved in the full volume ([Garren and Boozer, PoF (1991)] in the case of quasisymmetry).
 - ▶ Optimizing a single flux-surface can be successful strategy [Henneberg, NF (2019)]
 - ▶ Specific of energetic ions: perfectly optimized flux surface $s = s_0$ confines all energetic ions born at $s \leq s_0$.

Radially local description of J -maps: γ_c^*

$\gamma_c^*(\alpha, \lambda)$ at $s = 0.25$



$J(s, \alpha)$ polar map for $\lambda = 0.41/T$

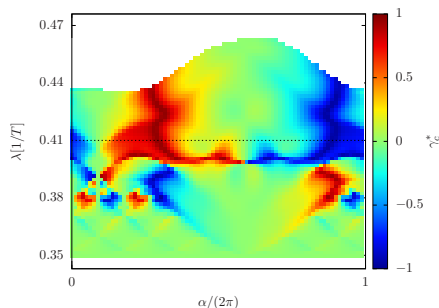


$$\gamma_c^* = \frac{2}{\pi} \arctan \frac{\partial_\alpha J}{|\partial_s J|} = \frac{2}{\pi} \arctan \frac{\overline{\mathbf{v}_M \cdot \nabla s}}{|\overline{\mathbf{v}_M \cdot \nabla \alpha}|}$$

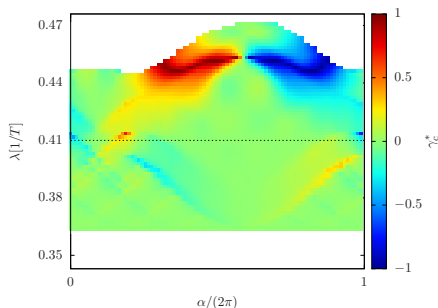
- $\gamma_c^* = 0$ where s -contours and J -contours are well aligned.
- $\gamma_c^* = \pm 1$ where s -contours and J -contours are orthogonal.
 - $\gamma_c^* = +1$ when $\overline{\mathbf{v}_M \cdot \nabla s}$ is directed outwards.

Interpretation of γ_c^* maps

$\beta = 1\%, s = 0.25$



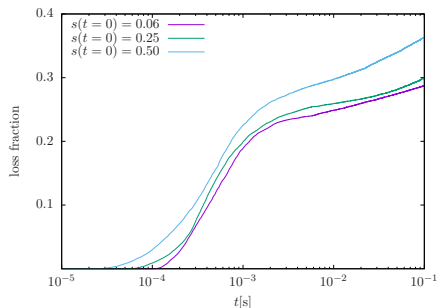
$\beta = 4\%, s = 0.25$



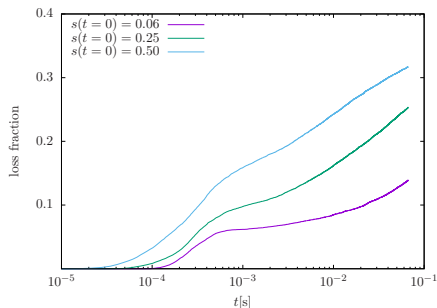
- When β increases, superbananas move to larger values of λ .
- Globally, the weight of the superbananas (area of the red and blue region in γ_c^* map) is reduced.
- ASCOT simulations confirm improvement of energetic ion loss fraction.
 - Can we use these maps to perform predictions?

Qualitative validation of γ_c^* maps with ASCOT calculations

$\beta = 1\%$

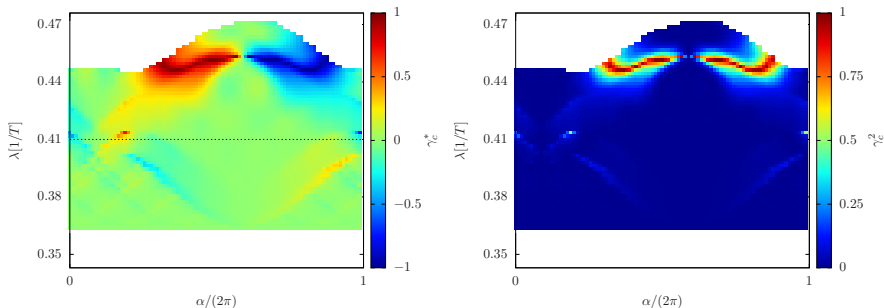


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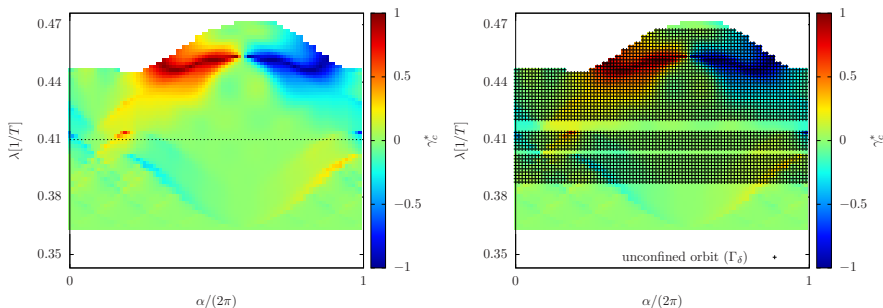
The Γ_c proxy



Proxy Γ_c [Nemov, PoP (2008)] is roughly an integral of $(\gamma_c^*)^2$.

- Measure of separation of J -contours from s -contours.
- Reduction of Γ_c typically correlates with improvement of energetic ion confinement.
- Employed successfully in optimization of QHS [Bader, JPP (2019)].
 - Can we go beyond this qualitative assesment?

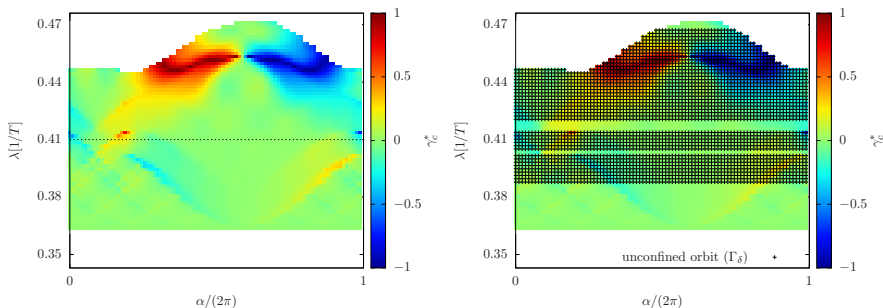
First approximation to modelling the fraction of losses



- Ions move at constant λ .
- λ -extension of red region should be greater concern than α -extension.
- Possible model: all ions born with λ where a superbanana exists are lost.
 - ▶ More precisely: orbit is unconfined if $\max(\gamma_c^*(\alpha|\lambda)) > \gamma_{th}$.
 - ▶ We choose $\gamma_{th} = 0.2$, corresponding approximately to $\frac{\mathbf{v}_M \cdot \nabla s}{\mathbf{v}_M \cdot \nabla \alpha} \approx \frac{1}{\pi}$

$$\Gamma_\delta = \frac{1}{2} \left\langle \int_{B_{MAX}^{-1}}^{B^{-1}} d\lambda \frac{B}{\sqrt{1 - \lambda B}} H\left(\max(\gamma_c^*(\alpha|\lambda)) - \gamma_{th}\right) \right\rangle$$

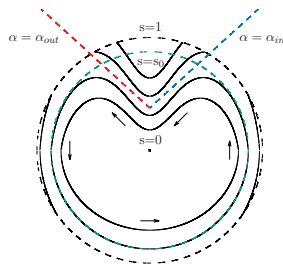
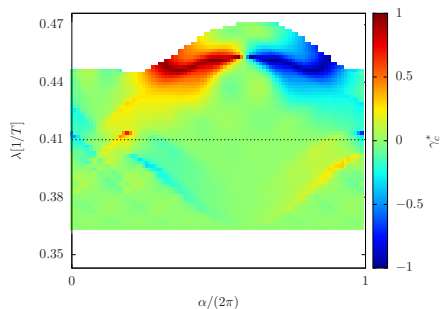
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A (small) step beyond the local approach

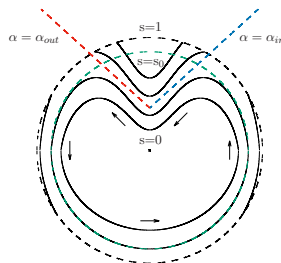
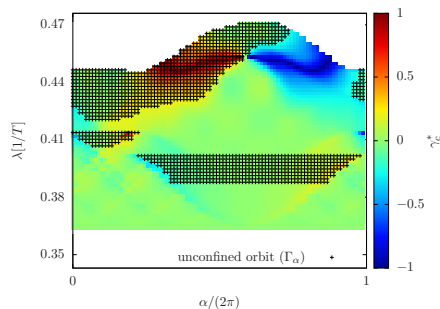


Ions at $s = s_0$ (dashed green) precess in α at constant J (thick black).

- Some ions reach $\alpha \approx \alpha_{out}$, where $\gamma_c^* \approx 1$, and escape.
- Others are tied to s_0 (inwards excursion around α_{in} , where $\gamma_c^* \approx -1$).
- Estimated fraction of prompt losses ($0 < \Gamma_\alpha < f_{trapped}$):

$$\Gamma_\alpha = \frac{1}{2} \left\langle \int_{B_{MAX}^{-1}}^{B^{-1}} d\lambda \frac{B}{\sqrt{1 - \lambda B}} H\left((\alpha_{out} - \alpha) \overline{\mathbf{v}_M \cdot \nabla \alpha}\right) H\left((\alpha - \alpha_{in}) \overline{\mathbf{v}_M \cdot \nabla \alpha}\right) \right\rangle$$

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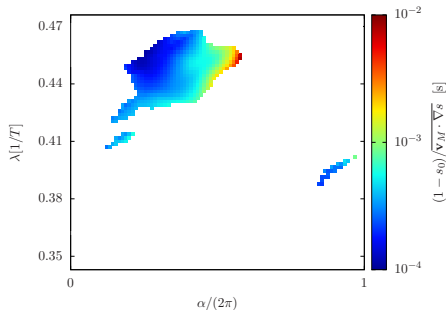
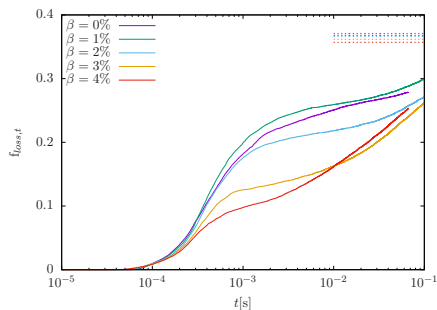


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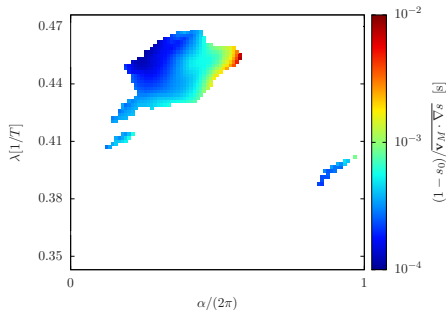
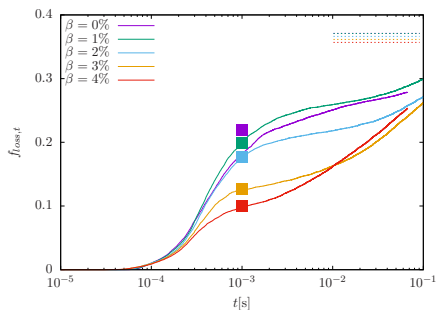
Model validation with ASCOT: time scale and total prompt losses



Model (squares) captures well several features of the ASCOT simulations (lines):

- $(1 - s_0)/\sqrt{\mathbf{v}_M \cdot \nabla s}$ evaluated around α_{out} gives the right time scale: $10^{-4} \text{ s} < t < 10^{-3} \text{ s}$.
- Value of total prompt losses at t *approximately* 10^{-3} s .
- Positive effect of β , even *jump* between 2% and 3%.

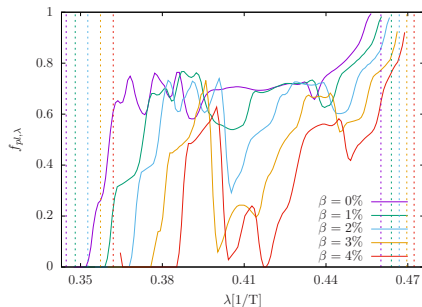
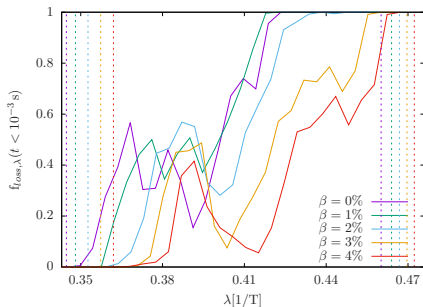
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Model validation with ASCOT: velocity distribution



Model captures well several features:

- For $\beta < 3\%$, particles with all velocities are expected to be lost.
- At $\beta = 3\%$, some ions with $\lambda \approx 0.41/T$ become confined.
- For $\beta > 3\%$, a larger range of λ has good confinement.

Model validation: overall configuration performance

Encapsulate performance on a single number (per flux-surface)

⇒ can be employed in a stellarator suite such as STELLOPT.

Two variations w.r.t. Nemov's Γ_c :

$$\check{\Gamma}_c = \frac{1}{2} \left\langle \int_{B_{\text{MAX}}^{-1}}^{B^{-1}} d\lambda \frac{B}{\sqrt{1 - \lambda B}} (\gamma_c^*)^2 \right\rangle = \frac{\pi}{2\sqrt{2}} \Gamma_c$$

$$\hat{\Gamma}_c = \frac{1}{2} \left\langle \int_{B_{\text{MAX}}^{-1}}^{B^{-1}} d\lambda \frac{B}{\sqrt{1 - \lambda B}} |\gamma_c^*| \right\rangle$$

Existence of superbananas:

$$\Gamma_\delta = \frac{1}{2} \left\langle \int_{B_{\text{MAX}}^{-1}}^{B^{-1}} d\lambda \frac{B}{\sqrt{1 - \lambda B}} H\left(\max(\gamma_c^*(\alpha|\lambda)) - \gamma_{th}\right) \right\rangle$$

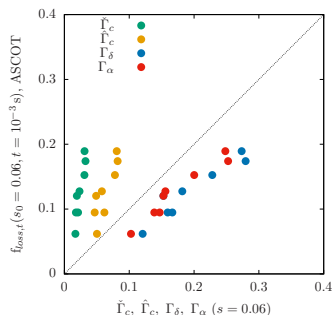
Our final model:

$$\Gamma_\alpha = \frac{1}{2} \left\langle \int_{B_{\text{MAX}}^{-1}}^{B^{-1}} d\lambda \frac{B}{\sqrt{1 - \lambda B}} H\left((\alpha_{\text{out}} - \alpha) \overline{\mathbf{v}_M \cdot \nabla \alpha}\right) H\left((\alpha - \alpha_{\text{in}}) \overline{\mathbf{v}_M \cdot \nabla \alpha}\right) \right\rangle$$

Model validation: overall configuration performance

- Repeat the calculation for main configurations of the OP1.2 campaign: KJM (incl. β scan), EIM, DBM, FTM.
- Compare:
 - ▶ Fraction of prompt losses for ions born at $s = 0.06$ calculated with ASCOT (y axis)
 - ▶ Model prediction at $s = 0.06$ (x axis).

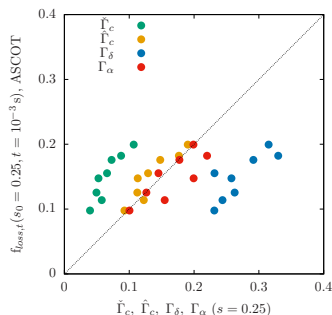
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- Γ_α good quantity for stellarator optimization.
- Optimization of just outer surface could be a good idea.



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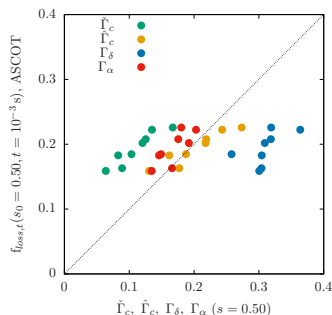
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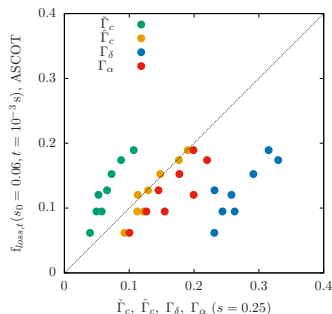
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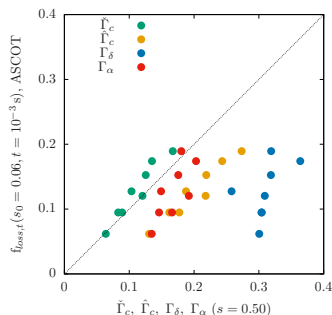
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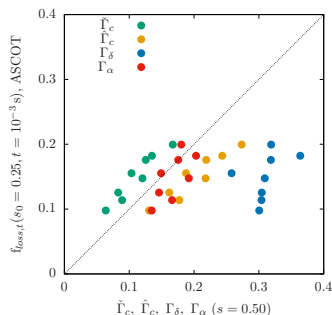
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Conclusions

We have developed a model that classifies orbits and succeeds in predicting configuration-dependent aspects of the prompt losses of energetic ions in stellarators.

Calculation takes **a few seconds on a single computer**, useful for:

- Stellarator optimization.
- Parameter scans.

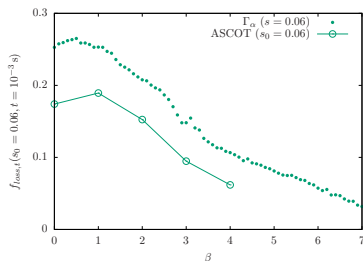
Next steps:

- Should work for other types of stellarators.
- Possible extensions of the model: E_r , pitch-angle collisions, ν -diffusion.
- Losses at longer t , associated to stochastic diffusion (but many more subtleties).

But it is clear that **quantitatively correct prediction requires a radially global code**.

- Many features of a particle trajectory are not determined by its initial point in phase space $(s, \alpha, I, \lambda, \nu)$ but specifically by the initial trapped-orbit in which it lies, $(s, \alpha, \lambda, \nu) \Rightarrow$ keep on using guiding-center codes but **with a more efficient initial distribution of markers**?

But...



Conclusions and ongoing work

Important theoretical result: bounce-averaged drift-kinetic equations are probably able to describe quantitatively neoclassical fast ion confinement. Need to be radially global.

- If the motion along the field line does not need to be resolved, equation could be solved much faster.
- We are extending (local) code KNOSOS to solve rigorously the radially global bounce-averaged drift kinetic equation (i.e., the bounce-averaged version of the equation solved by ASCOT):

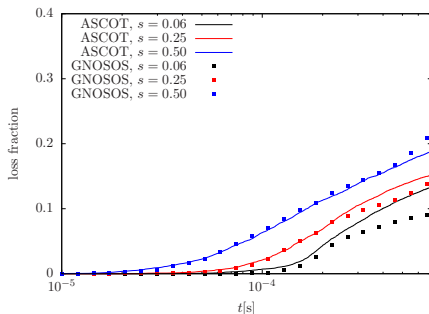
$$\partial_t F + \partial_\alpha J \partial_s F - \partial_s J \partial_\alpha F = C(F) + S$$

KNOSOS $\Rightarrow$ GNOSOS: **G**lobal **k**iNetic Orbit-averaging **S**olver for Stellarators
(* provisional name)

This can e.g. be solved by a Monte Carlo method that integrates

$$\begin{aligned}\dot{s} &= \overline{\mathbf{v}_M \cdot \nabla s} = \frac{m}{Ze\Psi_t\tau_b} \partial_\alpha J \\ \dot{\alpha} &= \overline{\mathbf{v}_M \cdot \nabla \alpha} = -\frac{m}{Ze\Psi_t\tau_b} \partial_s J\end{aligned}$$

Conclusions and ongoing work (II)



Working on the longer time scale:

- Stochastic losses have to do with diffusion caused by back and forth transition between trapped states.
 - ▶ Transition probabilities need to be calculated accurately.
 - ▶ Bounce-averages may need extra accuracy.
- Collision operator different than that of bulk species.